

Simulink Basics for Engineering Applications

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Basic concepts

- Simulink provides a graphical user interface (GUI) for building models as block diagrams, using click-and-drag mouse operations.
- Why use Simulink?
 - You can draw the models as you would with pencil and paper.
 - Designs are hierarchical, so that levels of details can be hidden or made explicit.
 - Simulations are interactive, so you can change parameters "on the fly".
 - Simulink includes a comprehensive block library of sinks, sources, linear and nonlinear components, and connectors.
 - C code or executables can be generated from a Simulink model by using Real-Time Workshop.



Associated Products - 1

- Stateflow
- Simulink Performance Tools
- Sateflow Coder
- Real-time Workshop
- Real-time Workshop Embedded Coder
- Real-time Workshop ADA Coder
- Real-time Windows Target





Associated Products - 2

- xPC Target
- xPC Targetbox
- xPC Target Embedded Option
- Simulink Report Generator
- Requirements Management Interface
- Virtual Reality
- SimMechanics
- Embedded Target MPC555





Simulink Blocksets

- Aerospace
- CDMA Reference
- Communications
- Dials and Gauges
- DSP
- Fixed Point
- Nonlinear Control Design
- Power Systems

A blockset is a library of blocks

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A Typical Simulink Model

• Includes Sources, Systems and Sinks.





A Typical Simulink Model

A typical Simulink model includes Source, System and Sink.





Block Choices in Simulink







Now, let's build a simple model!

This model plots the sign of the input signal.







Step1: Start Simulink and choose New then Model from the File menu.

| 🙀 Library: simulink3 | |
|--|--|
| <u>File Edit View Format H</u> elp | |
| Sources Sinks Continuous Discrete Math Functions & Tables Nonlinear Signals & Systems Blocksets & Toolboxes Simulink Block Library 4.0 Copyright (c) 1990-2000 The MathWorks, Inc. Demos | New Model Ctrl+N □pen Ctrl+D □lose Ctrl+W Save Ctrl+S Save Ctrl+S Save_as Source control |
| · | Model properties |
| untitled1 | Print Ctrl+P Print set <u>u</u> p |
| <u>File Edit View Simulation Format Tools Help</u> | Exit MATLAB Ctrl+Q |
| | |
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Step2: Copy the needed blocks by using Drag and Drop.



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Step3: Complete the connection.





Step4: Set the block parameters.

| Block Parameters: Sine Wave 📃 💌 | 属 untitled 1 | × | | | |
|------------------------------------|-----------------------------|---------------------|--------------|--------------------------------------|--------------|
| Sine Wave | <u>F</u> ile <u>E</u> dit ⊻ | (iew <u>S</u> imula | ation Forma | <u>t</u> T <u>o</u> ols <u>H</u> elp | |
| Output a sine wave. | | 3 🚭 🐰 | , B 🔒 | ାର ଜ 🎽 | 🖪 🦫 🛞 |
| Parameters | | | | | |
| Amplitude: | 5 | | | | |
| | | ₫ | ▶╡ | ►[] | |
| Frequency (rad/sec): | Sine∀ | Vave | Sign | Scope | |
| 1 | | | | | |
| Phase (rad): | | | | | |
| 0 | F 100% | | | ode45 | /_ |
| Sample time: | | | | | |
| 0 | Dout | ble click | a block t | to open its h | lock |
| Interpret vector parameters as 1-D | para | meters. | a DIOCK | to open its t | |
| OK Cancel Help Apply | | <u> </u> | | | |
| | | | - <u></u> | | -Ծ- 🗊 |
| mnower Partner Lend | | | | | |
| inpunction and the second | | | Oh | 10 Supercom | muter Center |

Example -- Step 5

Step5: Setup the simulation parameters.

| <u>S</u> imulation | Forma <u>t</u> | F <u>o</u> ols | <u>H</u> elp | | | | | | | | | |
|--------------------------------------|----------------|----------------|--------------|-----|------------------|-------------------------|-----------|-------------|----------------|-------------|-----------|---------|
| <u>S</u> tart | | (| Ctrl+T | | 🥠 Simu | lation Pa | rameters: | untitled | i1 | | _ 🗆 × | |
| Stop Simulatio | on naramet | ers (| Ctrl+F | | Solver | Workspar | ce 1/0 D |)iagnostic: | s Advanced | Real-Time \ | Norkshop | |
| ✓ <u>N</u> ormal <u>E</u> xternal | | | | | - Simul Start | ation time time: 0,0 | | Stop | time: 10.0 | | | |
| Start | time / | | | | - Solve Type: | r options | step 💌 | ode4 | 15 (Dormand-Pr | ince) | • | |
| | | | | | Max : | step size: | auto | | Relative toler | ance: 1e-3 | | |
| Stop | time 🦯 | | | | Min s | tep size: | auto | | Absolute tole | rance: auto | | |
| | | | | | Initial | step size: | auto | | | | | |
| Solve | er type 🦯 | | | | Outpu Refir | ut options ne output | | • | Refine f | actor: 1 | | K |
| | | | | unn | | | | OK | Cancel | Help | Apply | |
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Step6: Start simulation.





Need help?



Manipulating blocks



Labels and Annotations





Dividing a line into segments



Step1: Select the line.

Step2: Position the pointer on the line where you want the vertex.

Step3: While holding down the Shift key, press and hold down the mouse button.

Step4: Drag the pointer to the desired location.

Step5: Release the mouse button and Shift key.



Dividing a line into segments



Step1: Position the pointer on the vertex, then press and hold down the mouse button.

Step2: Drag the pointer to the desired location.

Step3: Release the mouse button.





Inserting a block in a line



Step1: Position the pointer over the block and press the left mouse button.

Step2: Drag the block over the line in which you want to insert the block.

Step3: Release the mouse button to drop the block on the line.



Example 2: Revisit van der Pol's equation

• Recall that the equation is

 d^2x/dt^2 - $\mu(1\text{-}x^2)dx/dt + x = 0$

• Convert to first order ODEs using

 $dy_1/dt = y_2$ $dy_2/dt = \mu(1-y_1^2)y_2-y_1$

where $y_1 = x$, and $y_2 = dx/dt$

- In Simulink, start with two integrator blocks, one for y_1 , another for y_2 .
- Then use Sum, Product and Gain blocks to create dy_1/dt and dy_2/dt as inputs to the integrator blocks.



Simulink model of van der Pol



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Example 3: Leaky Integrator

- An ideal integrator is described by the equation dy/dt = x(t), where y(t) is the output and x(t) is the input.
- A leaky integrator is described by the equation $dy/dt = x(t) \mu y(t), \mu > 0$
- The solution, for x(t) = Ku(t), is $y(t) = (K/\mu) (1 - e^{-\mu t})u(t)$
- If we want the steady state output for a constant input to be the same constant, we can add a gain term of μ at the output. $y_o(t) = \mu y(t)$



Simulink model for leaky integrator





Output of leaky integrator Output $\mu = 0.1$ $\mathbf{K} = 1$ -5 . 0 Time offset: 0 4 $\mu = 0.1$ K = 4Time offset: 0 Time offset: 0 $\mu = 0.9$ K = 4 Empower. Partner. Lead. Time offset: 0 Time offset: 0

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Subsystems







Subsystems can hide the complexity of the subsystems from the user, which can make your model clearer. There are two ways to create Subsystems.

You can create a Subsystem by adding the Subsystem block from Signals & Systems. Then you can edit the Subsystem by doubling clicking the Subsystem block.
You can create create the subsystem by grouping blocks from an existing system.

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Leaky integrator subsystem



2. Choose Create Subsystem from the Edit menu

| Can't undo | | Ctrl+Z | |
|--------------|-------------|--------|--|
| Can't redo | | Ctrl+Y | |
| Cut | | Ctrl+X | |
| Сору | | Ctrl+C | |
| Paste | | Ctrl+V | |
| Clear | | Delete | |
| Select all | | Ctrl+A | |
| Copy model t | o clipboard | | |
| Find | | Ctrl+F | |
| Create subsy | Ctrl+G | | |
| Mask subsys | Ctrl+M | | |
| Look under m | Ctrl+U | | |
| Link options | | Þ | |
| | | | |





Using the leaky integrator subsystem

• You can now use the leaky integrator subsystem like any other block



• Double clicking the subsystem opens the subsystem and shows the blocks inside



Example 4: Envelope Detection using Leaky Integrator





Stepped Sine Wave



Results for mu =1 for Leaky Integrator

output



Time offset: 0





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Comparing Results for different mu values



Mu = 1

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$$Mu = 5$$



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